

Amendments to the Specification:

Please replace paragraphs 24, 33, and 35 with the following amended paragraphs:

[0024] The steering assembly 50 and the power unit 60 are interconnected and are rotatably fastened to the pivot frame 40 such that the drive wheel 66 of the power unit 60 rotates about the drive axis Y2 as the tiller 42 of the steering assembly 50 is rotated about the steering axis Y1. In the preferred embodiment of the invention, the tiller mount 46 5 and the transmission housing 62 are fastened to the inner race of a steering bearing on opposite sides of the bearing. The steering bearing 99 is then fastened to the pivot frame 40 through the outer race of the steering bearing 99. This interconnects the steering assembly 50 and the power unit 60 such that they rotate together and rotatably fastens them to the pivot frame 40. Alternatively, the steering assembly 50 and power unit 60 could be fastened to the outer race of the steering bearing and the steering bearing fastened to the pivot frame 40 through the inner race or any other suitable method could be used that would interconnect the steering assembly 50 and the power unit 60 and rotatably fasten them to the pivot frame 40. The orientation of the power unit 60, and therefore the direction of travel of the drive wheel 66, is therefore determined by the orientation of the steering assembly 50, which controls the direction of truck motion.

[0033] The transmission housing 162 is rotatably fastened to the pivot frame 40 such that the power unit 160 can rotate about the steering axis Y3. In this embodiment, the transmission housing 162 includes a pivot arm which extends vertically from the top of the transmission housing 162 and is rotatably fastened to the pivot frame 40 through a ~~pair of~~

~~bearings~~ steering bearing 99. Alternatively, the transmission housing 162 could also be fastened to a steering bearing, which is then fastened to a surface of the pivot frame 40, as described in the preferred embodiment above. The orientation of the power unit 160, and therefore the direction of travel of the drive wheel 66, is therefore determined by the orientation of the tiller 52, which controls the direction of truck motion.

[0035] The tilt of the steering axis Y3 is created by tilting the axis of rotation of the ~~bearings~~ steering bearing 99 between the pivot frame 40 and the transmission housing 162 toward the forks by α degrees from vertical. To do this, the ~~bearings~~ steering bearing 99 is fastened to the pivot frame 40 such that the axis of rotation of the ~~bearings~~ steering bearing 99 is tilted toward the forks 24, 25 the desired amount from vertical. The transmission housing 162 is fastened to the ~~bearings~~ steering bearing 99 such that the steering axis Y3 and the axis of rotation of the ~~bearings~~ steering bearing 99 are aligned. Since the steering axis Y3 is aligned with the axis of rotation of the bearings, the steering axis Y3 will also be tilted toward the forks, the desired amount from vertical.